

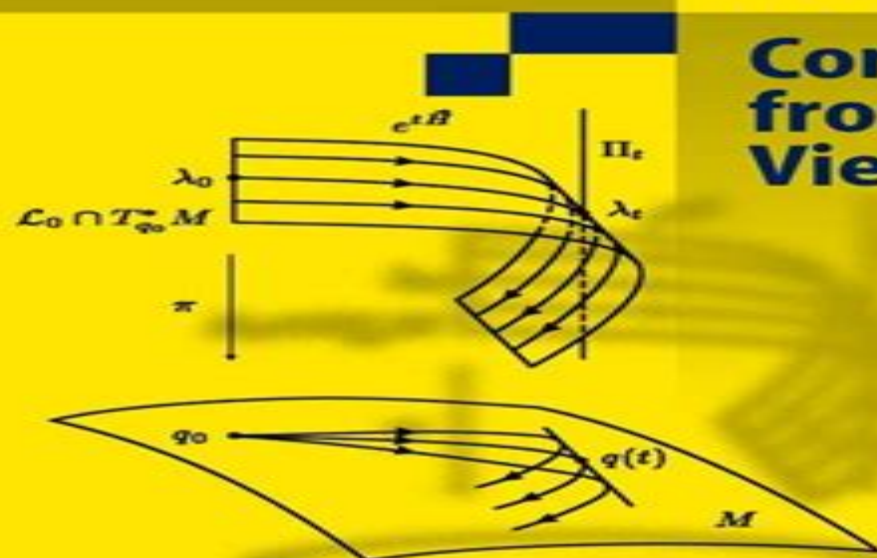
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II

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Control Theory from the Geometric Viewpoint



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Control Theory From The Geometric Viewpoint

Casti



Control Theory From The Geometric Viewpoint:

Control Theory from the Geometric Viewpoint Andrei A. Agrachev, Yuri Sachkov, 2004-04-15 This book presents some facts and methods of Mathematical Control Theory treated from the geometric viewpoint It is devoted to finite dimensional deterministic control systems governed by smooth ordinary differential equations The problems of controllability state and feedback equivalence and optimal control are studied Some of the topics treated by the authors are covered in monographic or textbook literature for the first time while others are presented in a more general and flexible setting than elsewhere Although being fundamentally written for mathematicians the authors make an attempt to reach both the practitioner and the theoretician by blending the theory with applications They maintain a good balance between the mathematical integrity of the text and the conceptual simplicity that might be required by engineers It can be used as a text for graduate courses and will become most valuable as a reference work for graduate students and researchers Introduction to Geometric Control Yuri Sachkov, 2022-07-02 This text is an enhanced English version of the Russian edition published in early 2021 and is appropriate for an introductory course in geometric control theory The concise presentation provides an accessible treatment of the subject for advanced undergraduate and graduate students in theoretical and applied mathematics as well as to experts in classic control theory for whom geometric methods may be introduced Theory is accompanied by characteristic examples such as stopping a train motion of mobile robot Euler elasticae Dido's problem and rolling of the sphere on the plane Quick foundations to some recent topics of interest like control on Lie groups and sub Riemannian geometry are included Prerequisites include only a basic knowledge of calculus linear algebra and ODEs preliminary knowledge of control theory is not assumed The applications problems oriented approach discusses core subjects and encourages the reader to solve related challenges independently Highly motivated readers can acquire working knowledge of geometric control techniques and progress to studying control problems and more comprehensive books on their own Selected sections provide exercises to assist in deeper understanding of the material Controllability and optimal control problems are considered for nonlinear nonholonomic systems on smooth manifolds in particular on Lie groups For the controllability problem the following questions are considered controllability of linear systems local controllability of nonlinear systems Nagano Sussmann Orbit theorem Rashevskii Chow theorem Krener's theorem For the optimal control problem Filippov's theorem is stated invariant formulation of Pontryagin maximum principle on manifolds is given second order optimality conditions are discussed and the sub Riemannian problem is studied in detail Pontryagin maximum principle is proved for sub Riemannian problems solution to the sub Riemannian problems on the Heisenberg group the group of motions of the plane and the Engel group is described Geometry of Submanifolds and Homogeneous Spaces Andreas Arvanitoyeorgos, George Kaimakamis, 2020-01-03 The present Special Issue of Symmetry is devoted to two important areas of global Riemannian geometry namely submanifold theory and the geometry of Lie groups and homogeneous spaces

Submanifold theory originated from the classical geometry of curves and surfaces Homogeneous spaces are manifolds that admit a transitive Lie group action historically related to F Klein s Erlangen Program and S Lie s idea to use continuous symmetries in studying differential equations In this Special Issue we provide a collection of papers that not only reflect some of the latest advancements in both areas but also highlight relations between them and the use of common techniques Applications to other areas of mathematics are also considered

Topological Obstructions to Stability and Stabilization Wouter Jongeneel,Emmanuel Moulay,2023-05-16 This open access book provides a unified overview of topological obstructions to the stability and stabilization of dynamical systems defined on manifolds and an overview that is self contained and accessible to the control oriented graduate student The authors review the interplay between the topology of an attractor its domain of attraction and the underlying manifold that is supposed to contain these sets They present some proofs of known results in order to highlight assumptions and to develop extensions and they provide new results showcasing the most effective methods to cope with these obstructions to stability and stabilization Moreover the book shows how Borsuk s retraction theory and the index theoretic methodology of Krasnosel skii and Zabreiko underlie a large fraction of currently known results This point of view reveals important open problems and for that reason this book is of interest to any researcher in control dynamical systems topology or related fields

Linear Algebra for Control Theory Paul Van Dooren,Bostwick Wyman,2012-12-06 During the past decade the interaction between control theory and linear algebra has been ever increasing giving rise to new results in both areas As a natural outflow of this research this book presents information on this interdisciplinary area The cross fertilization between control and linear algebra can be found in subfields such as Numerical Linear Algebra Canonical Forms Ring theoretic Methods Matrix Theory and Robust Control This book s editors were challenged to present the latest results in these areas and to find points of common interest This volume reflects very nicely the interaction the range of topics seems very wide indeed but the basic problems and techniques are always closely connected And the common denominator in all of this is of course linear algebra This book is suitable for both mathematicians and students

Perturbation Theory Giuseppe Gaeta,2022-12-16 This volume in the Encyclopedia of Complexity and Systems Science Second Edition is devoted to the fundamentals of Perturbation Theory PT as well as key applications areas such as Classical and Quantum Mechanics Celestial Mechanics and Molecular Dynamics Less traditional fields of application such as Biological Evolution are also discussed Leading scientists in each area of the field provide a comprehensive picture of the landscape and the state of the art with the specific goal of combining mathematical rigor explicit computational methods and relevance to concrete applications New to this edition are chapters on Water Waves Rogue Waves Multiple Scales methods legged locomotion Condensed Matter among others while all other contributions have been revised and updated Coverage includes the theory of Poincare Birkhoff Normal Forms aspects of PT in specific mathematical settings Hamiltonian KAM theory Nekhoroshev theory and symmetric systems technical problems arising in PT

with solutions convergence of series expansions diagrammatic methods parametric resonance systems with nilpotent real part PT for non smooth systems and on PT for PDEs write out this acronym partial differential equations Another group of papers is focused specifically on applications to Celestial Mechanics Quantum Mechanics and the related semiclassical PT Quantum Bifurcations Molecular Dynamics the so called choreographies in the N body problem as well as Evolutionary Theory Overall this unique volume serves to demonstrate the wide utility of PT while creating a foundation for innovations from a new generation of graduate students and professionals in Physics Mathematics Mechanics Engineering and the Biological Sciences

Differential Geometric Control Theory Roger W. Brockett, 1983 **Nonlinear System Theory** Casti, 1985-02-21 **Nonlinear System Theory** **Geometric Control Theory** Velimir Jurdjevic, 1997 Geometric control theory is concerned with the evolution of systems subject to physical laws but having some degree of freedom through which motion is to be controlled This book describes the mathematical theory inspired by the irreversible nature of time evolving events The first part of the book deals with the issue of being able to steer the system from any point of departure to any desired destination The second part deals with optimal control the question of finding the best possible course An overlap with mathematical physics is demonstrated by the Maximum principle a fundamental principle of optimality arising from geometric control which is applied to time evolving systems governed by physics as well as to man made systems governed by controls Applications are drawn from geometry mechanics and control of dynamical systems The geometric language in which the results are expressed allows clear visual interpretations and makes the book accessible to physicists and engineers as well as to mathematicians

New Directions in Applied Mathematics P.J. Hilton, G.S. Young, 2012-12-06 It is close enough to the end of the century to make a guess as to what the Encyclopedia Britannica article on the history of mathematics will report in 2582 We have said that the dominating theme of the Nineteenth Century was the development and application of the theory of functions of one variable At the beginning of the Twentieth Century mathematicians turned optimistically to the study of functions of several variables But wholly unexpected difficulties were met new phenomena were discovered and new fields of mathematics sprung up to study and master them As a result except where development of methods from earlier centuries continued there was a recoil from applications Most of the best mathematicians of the first two thirds of the century devoted their efforts entirely to pure mathematics In the last third however the powerful methods devised by then for higher dimensional problems were turned onto applications and the tools of applied mathematics were drastically changed By the end of the century the temporary overemphasis on pure mathematics was completely gone and the traditional interconnections between pure mathematics and applications restored This century also saw the first primitive beginnings of the electronic calculator whose development in the next century led to our modern methods of handling mathematics

Linear Dynamical Systems Casti, 1987-03-19 **Linear Dynamical Systems** *SIAM Journal on Control and Optimization* Society for Industrial and Applied Mathematics, 2007 **Attainable Region Theory** David Ming, David

Glasser, Diane Hildebrandt, Benjamin Glasser, Matthew Metzger, 2016-10-10 Recipient of the 2019 Most Promising New Textbook Award from the Textbook Academic Authors Association TAA The authors of Attainable Region Theory An Introduction to an Choosing Optimal Reactor make what is a complex subject and decades of research accessible to the target audience in a compelling narrative with numerous examples of real world applications TAA Award Judges February 2019 Learn how to effectively interpret select and optimize reactors for complex reactive systems using Attainable Region theory Teaches how to effectively interpret select and optimize reactors for complex reactive systems using Attainable Region AR theory Written by co founders and experienced practitioners of the theory Covers both the fundamentals of AR theory for readers new to the field as well as advanced AR topics for more advanced practitioners for understanding and improving realistic reactor systems Includes over 200 illustrations and 70 worked examples explaining how AR theory can be applied to complex reactor networks making it ideal for instructors and self study Interactive software tools and examples written for the book help to demonstrate the concepts and encourage exploration of the ideas Discrete and Continuous Dynamical Systems ,2005 **Motion Planning for Multi-spacecraft Interferometric Imaging Systems** Islam I. Hussein, 2005 *Analysis and Singularities* V. M. Zakalyukin, A. A. Davydov, 2007 **Mathematical Reviews** ,2005
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